



Session with Nick (project 1) Robotic arm



Summarize Rigging methods

Robot arm modelling - animation - rendering

Video and animation compositing and effects with after effect

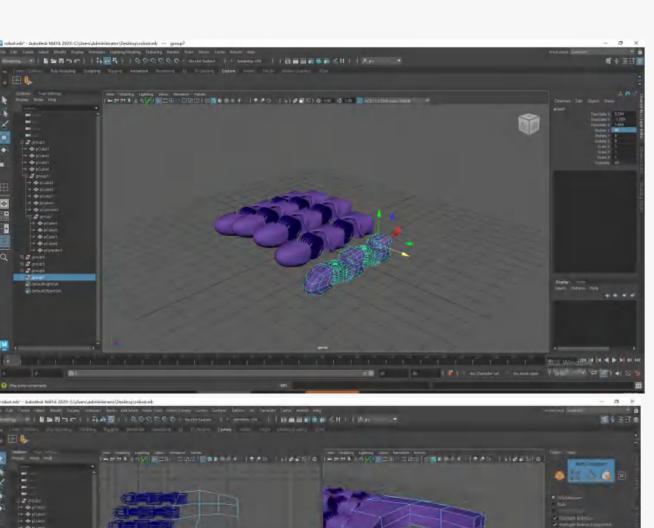
1:Use Joint+IK+Curve & pole vector +point+orient constrain for rigging

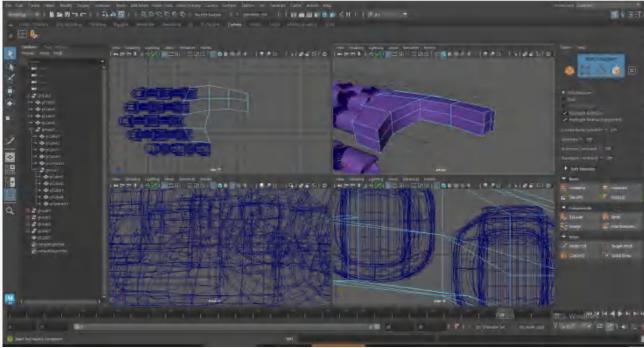
2:Use hierarchical relationships and parent constraints

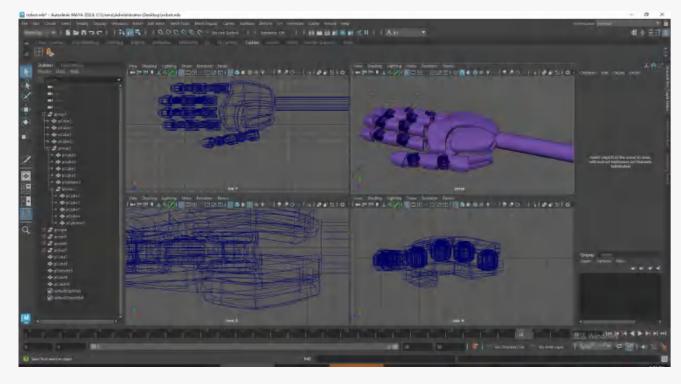
3:Use Node & Python data to establish constraints

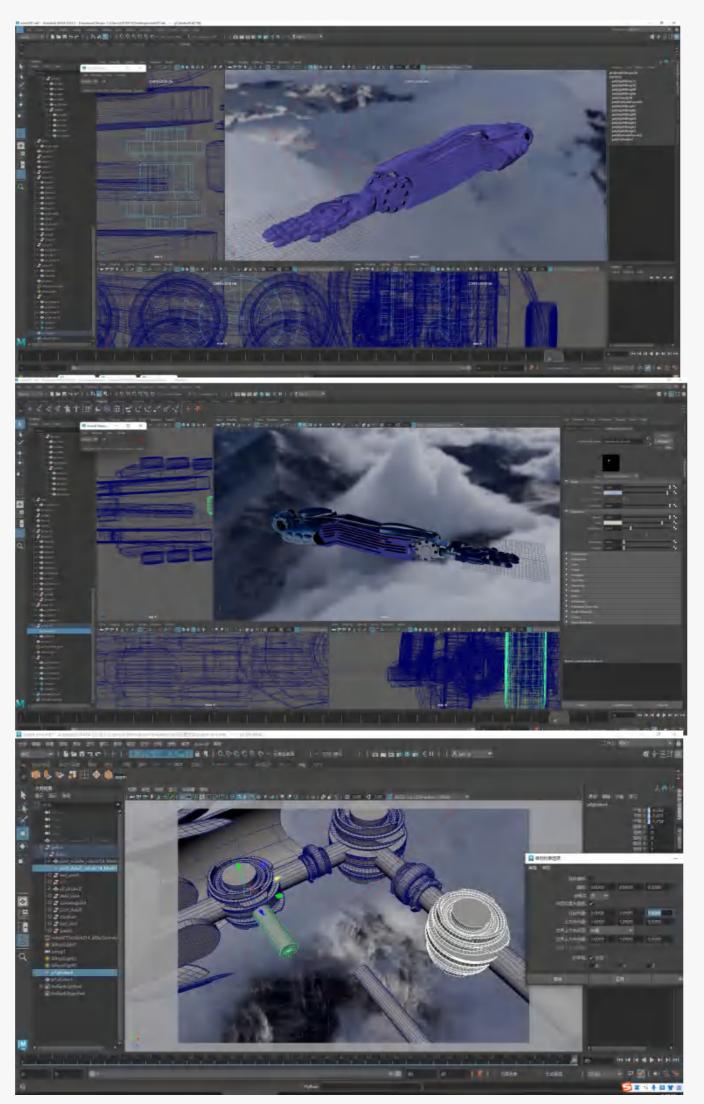
Robotic arm-Modeling process & Reference

Hand – Palm – Fist – Back of the hand – Knuckles – Fingers – Nail
Thumb – Index finger – Middle finger – Ring finger – Little finger – Finger prints – Finger tips

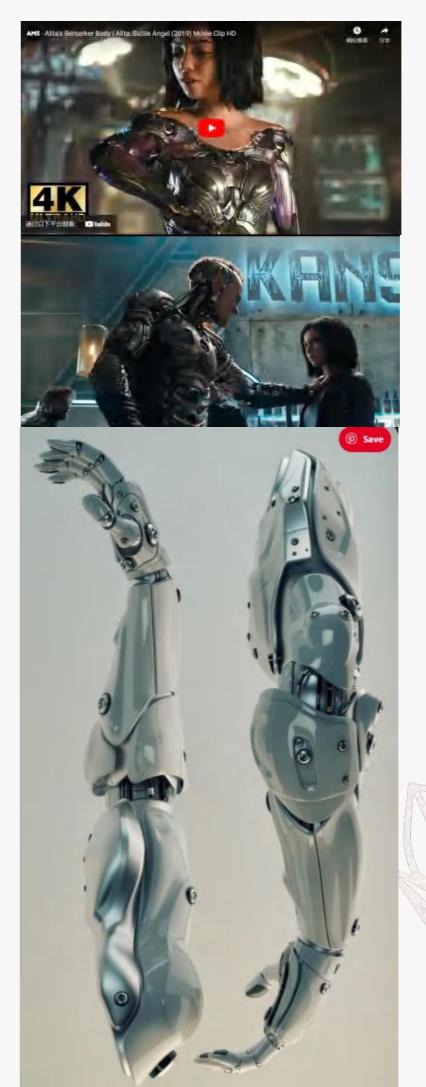


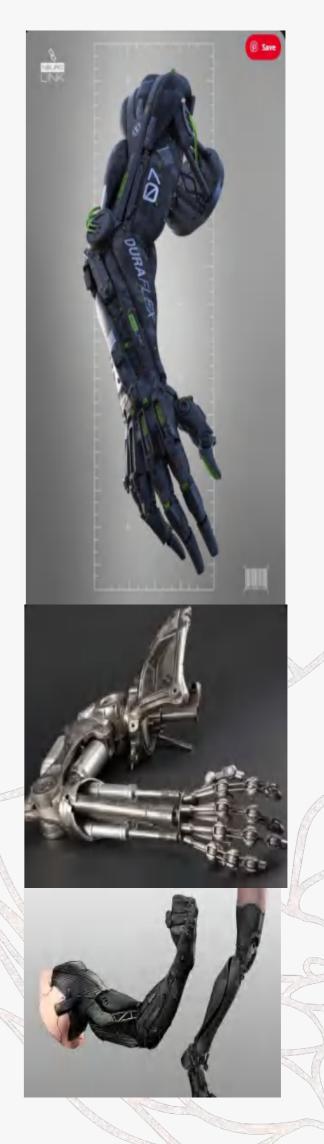






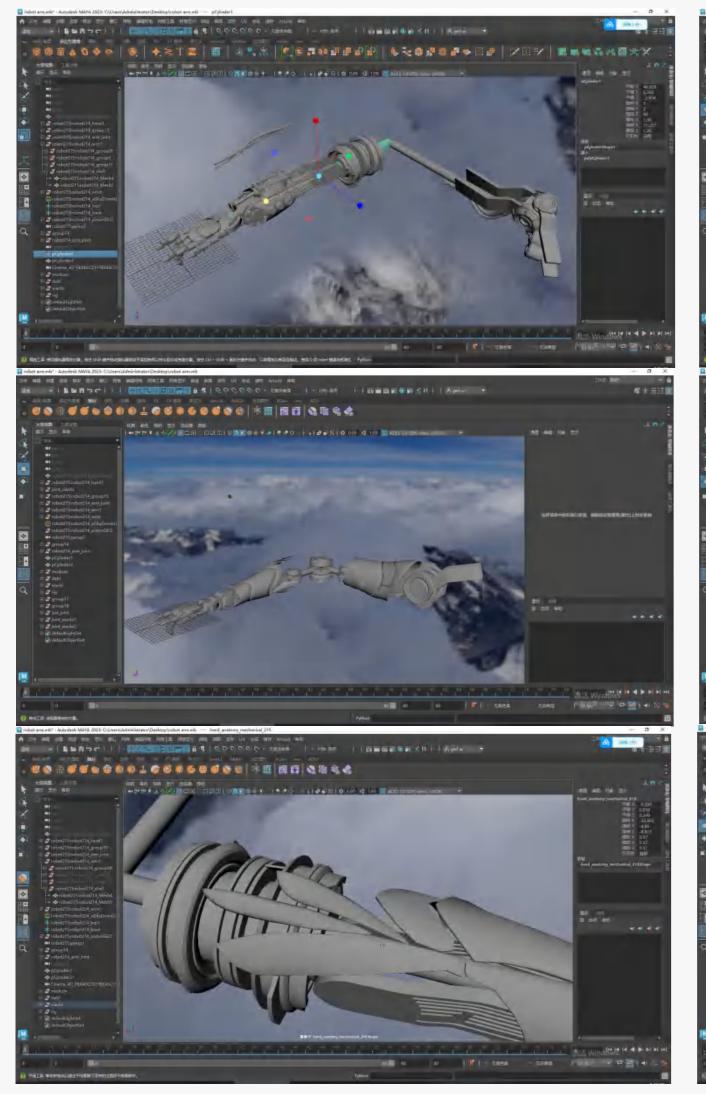
Alita Battle Angel: Bar Fight Round arm mecha shell

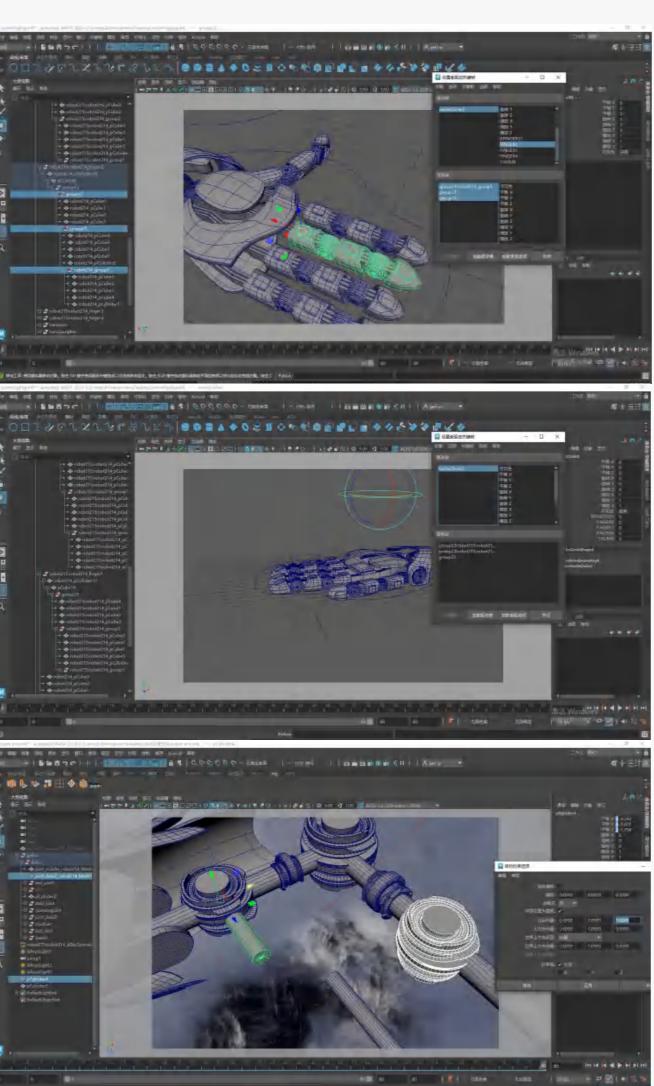


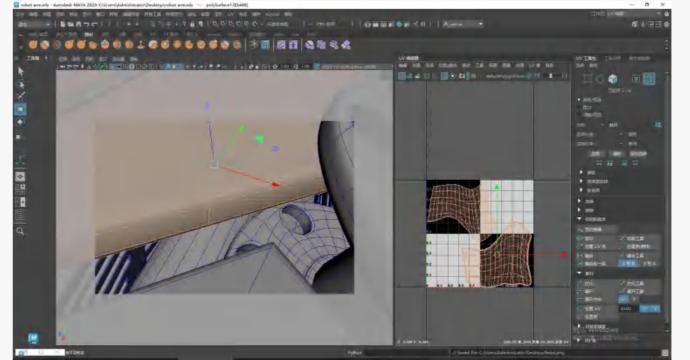


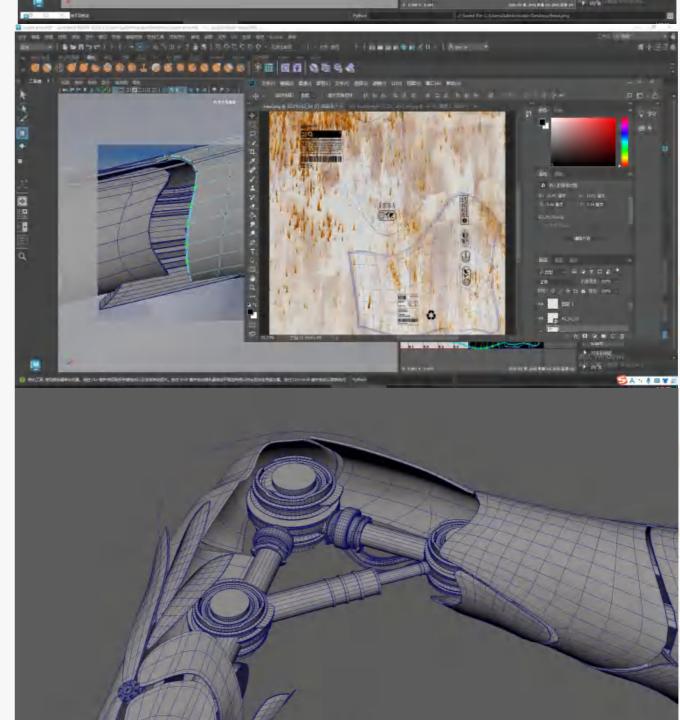
Robotic arm-Arms structure and UV

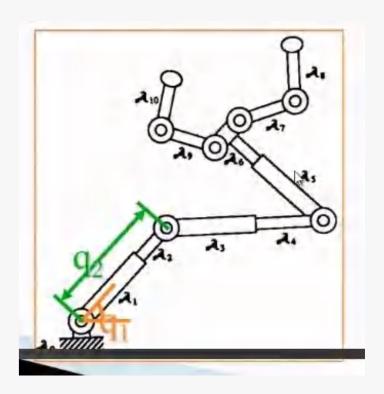
Arm— Forearm — Upper arm — Wrist — Elbow — Elbow joint — Shoulder





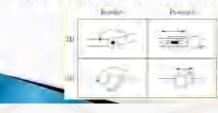






1.1.1 机器人的符号表示

机器人机械臂是由一系列通过关节相连的连杆组成的运动链。关节通常包括转动(旋转)和平动(移动或平移)两种。转动关节就像是一个铰链,使得与其相连的两个杠杆可以相互转动。平动关节使得与其相连的两个杠杆之间可以相互平移。我们使用R来指伏转动关节。用P来指伏平动关节。



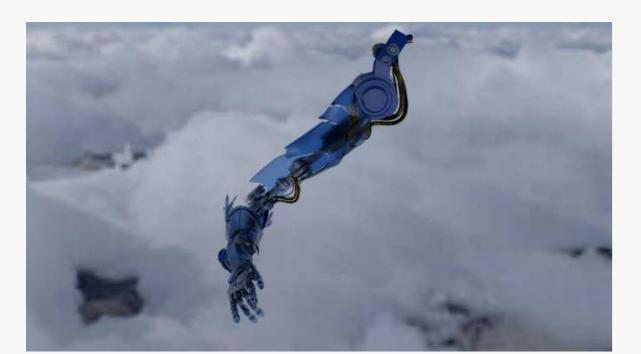
1.1.2 位形空间

- 机械臂的位形是指机械臂上各点位置的一个完整规范。所有位形的集合称为位形空间。
- 我们将使用关节变量值的集合来表示机器人的位形。 我们用 q 来表示这个集合的向量;并且当关节变量 依此取值为 q_1, \dots, q_n 时(转动关节对应 $q_i = \theta_i$,平 动关节对应 $q_i = d_i$),称机器人处于位形 q_n

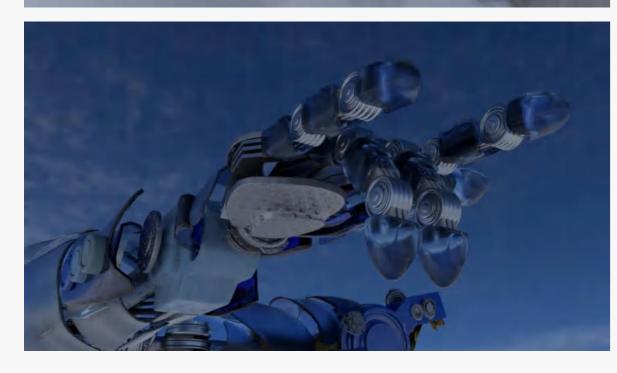


Making model material

Transparent plastic material

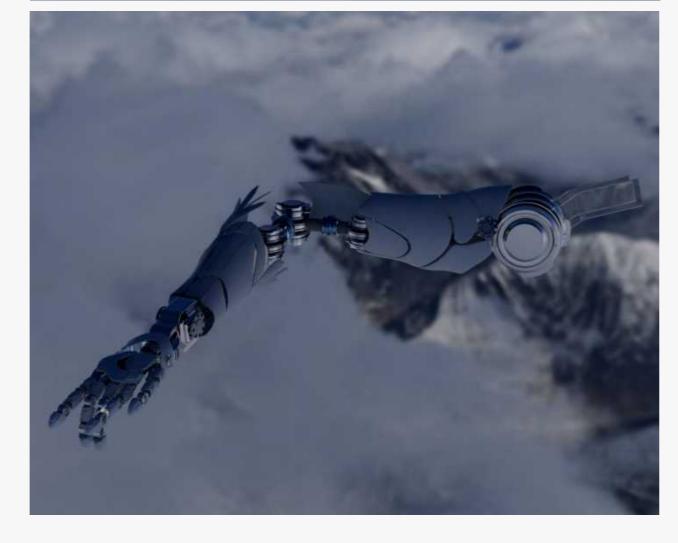


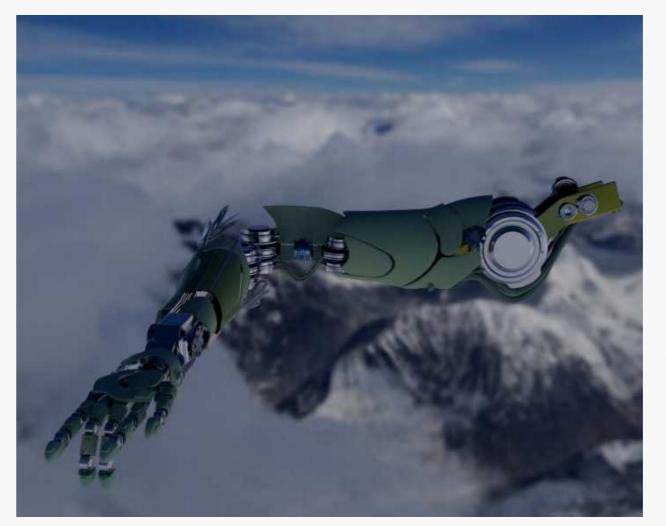




Smooth steel





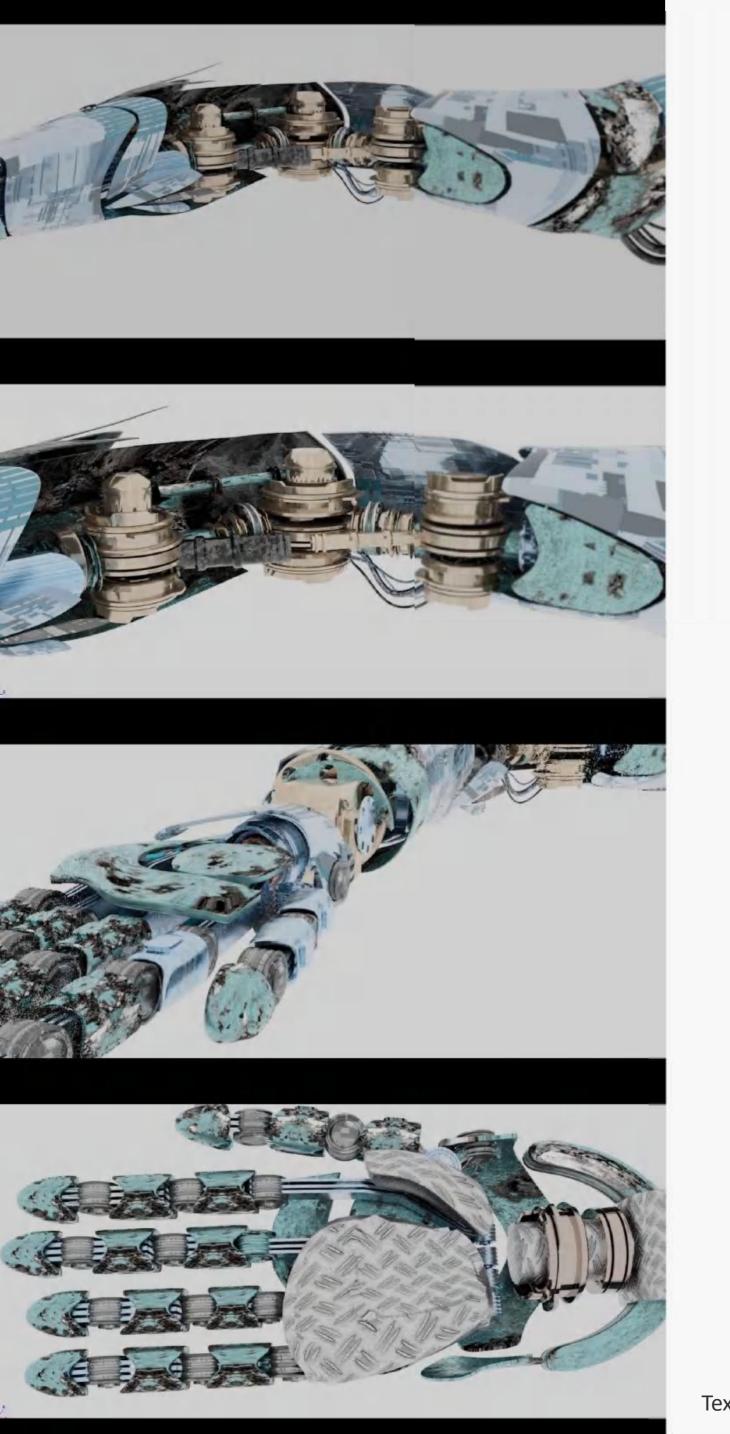


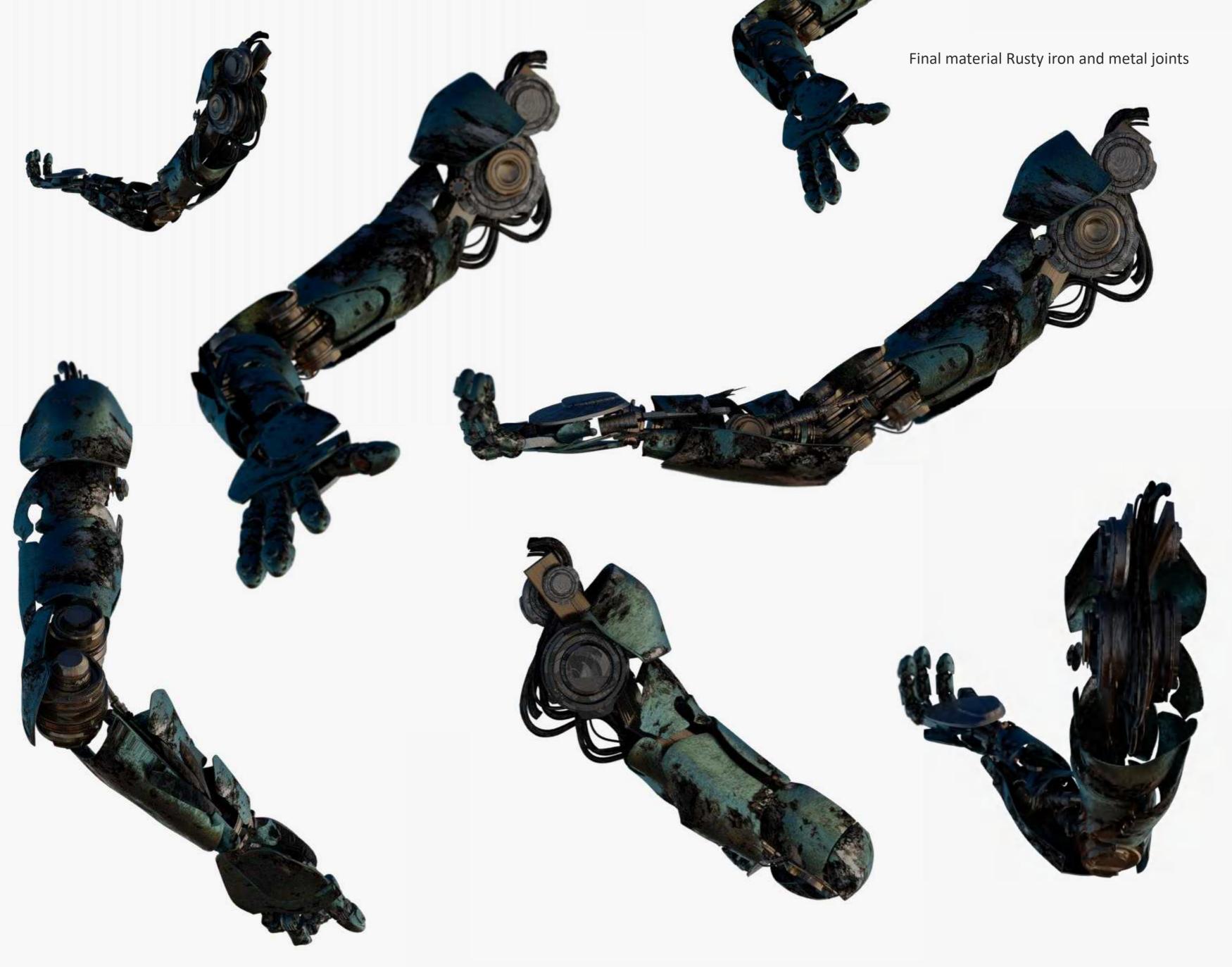




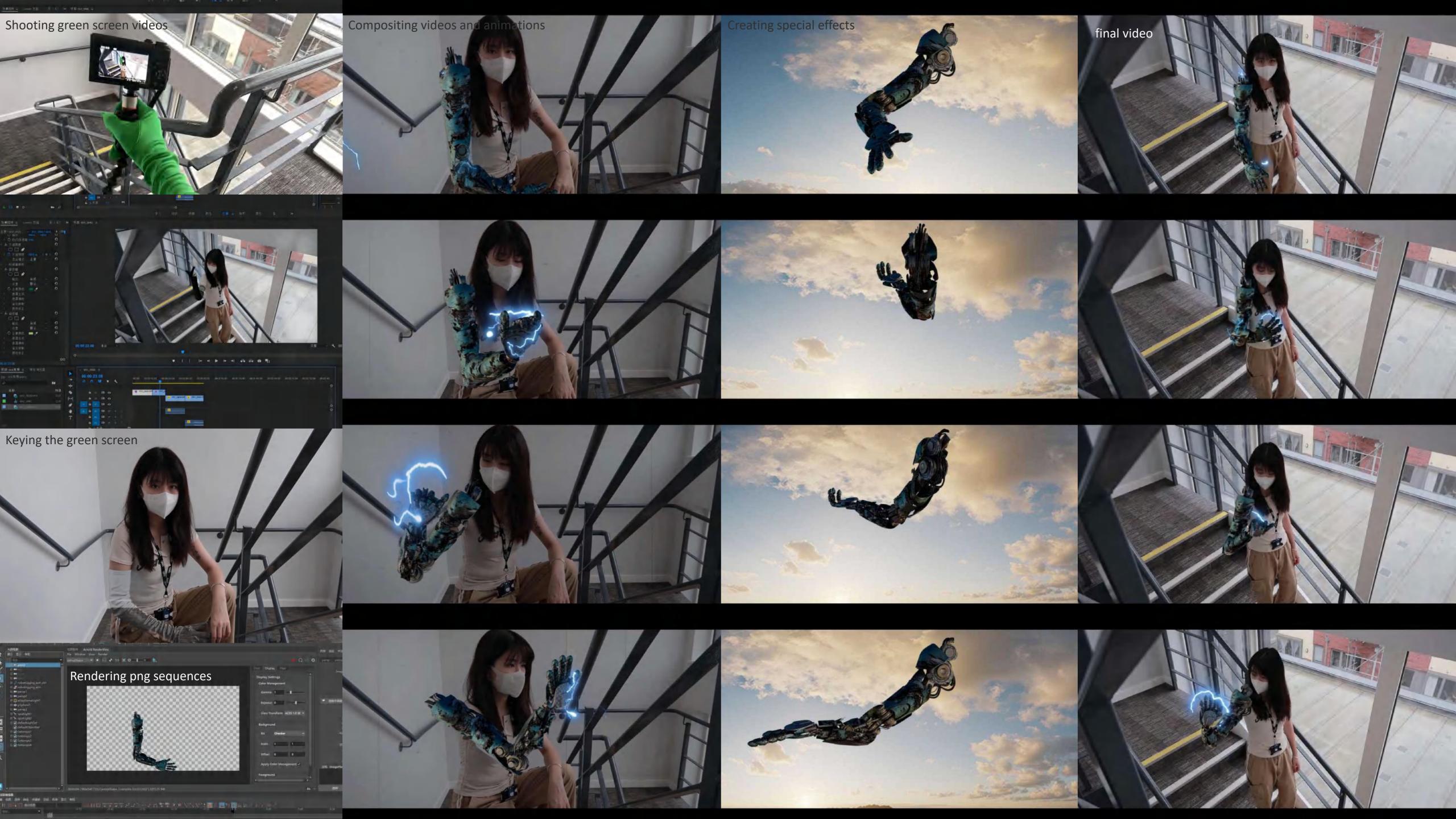




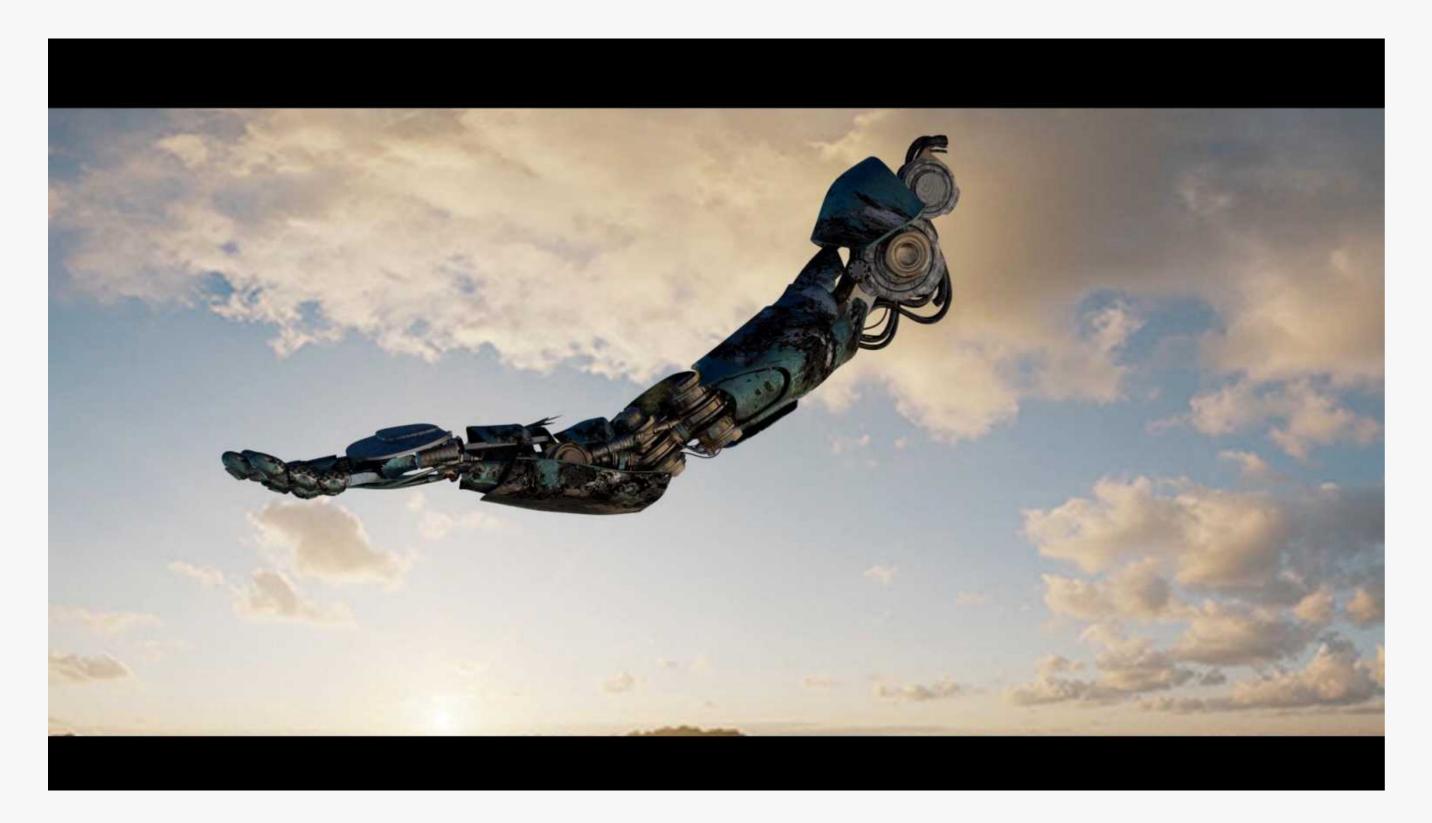




Texturing the palm of the hand with Arnold's mapping/Diffusion/Bump/Displacement/Deformation







• 3:Use Node & Python to establish constraints

- use the node editor to control the y-axis of the curve and to control the rotation details by adjusting the object's rotation angle and
- inputting and outputting the maximum and minimum values

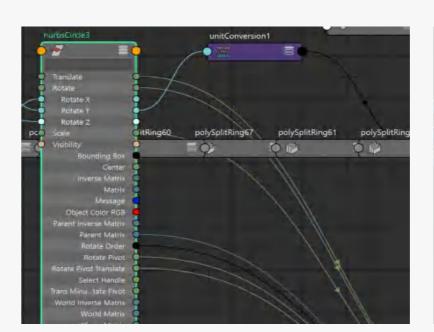
Summarize Rigging methods

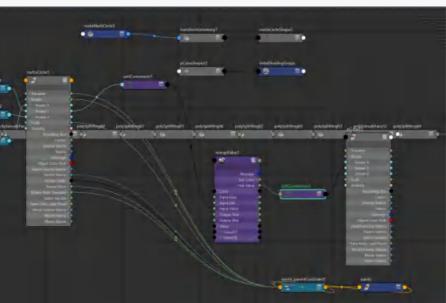
1:Use Joint+IK+Curve & pole vector +point+orient constrain for rigging

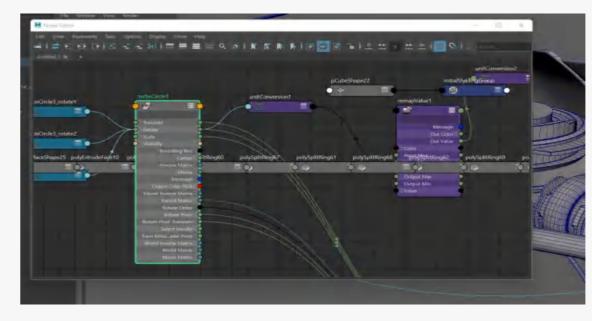
Create Joints – create IK handle – create locator – control knee joint with Twist – connect locator and IK handle with pole vector – create curve – use curve and IK handle to constrain displacement with point – curve lies in the joint of the forearm to establish orient constraint to control rotation -Finish Use loc to control the joint direction, use curve to control the upper arm and forearm, hand.

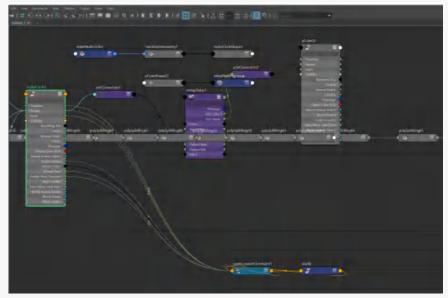
2:Use hierarchical relationships and parent constraints

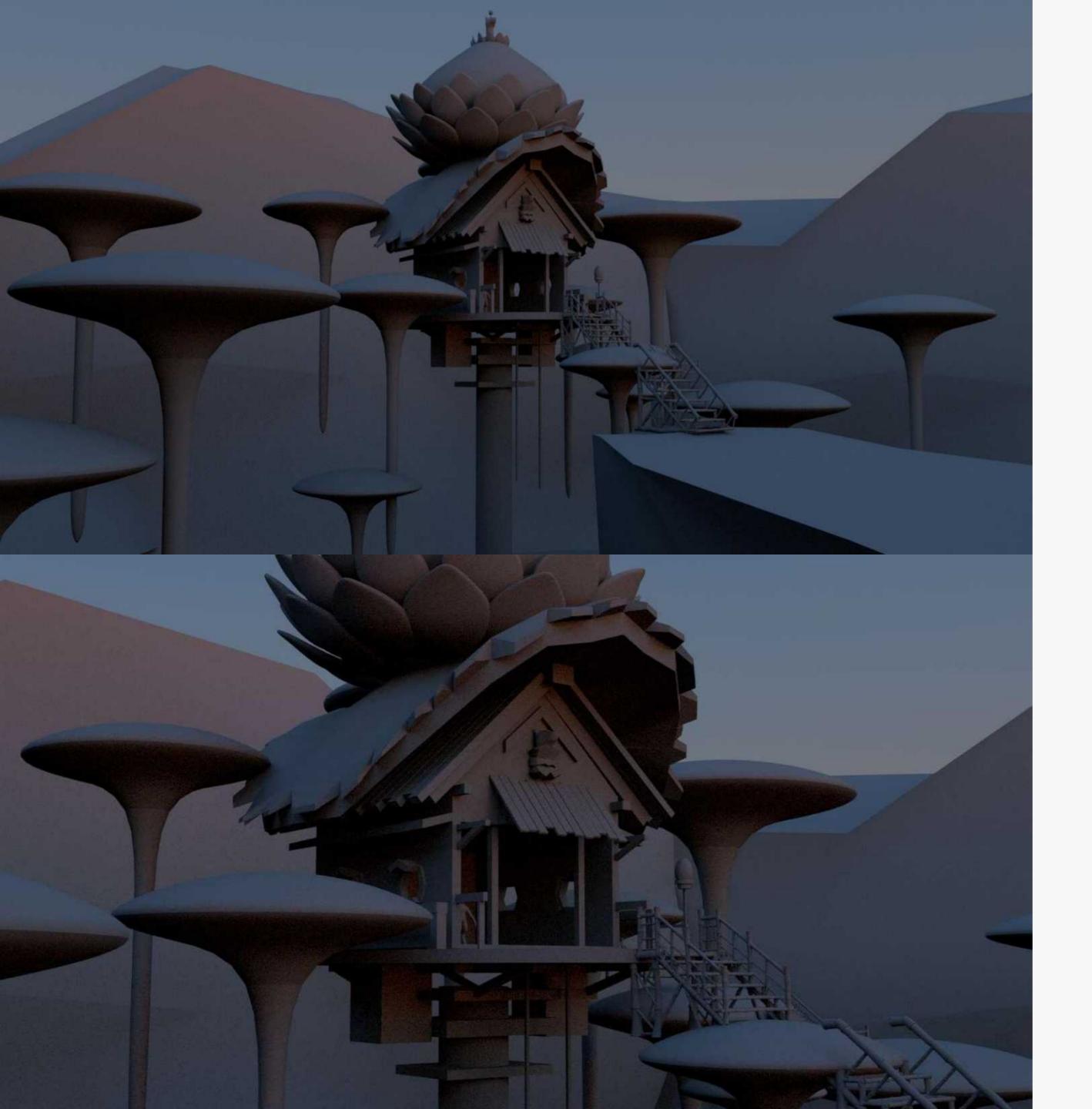
- 1:clean hierarchical relationships
- 2:control the group point
- 3:set curve
- 4:set parent constrain -to every group
- 5:set curve group-to control every poly modeling











Sessions with George (project 2) 3 previz ideas



Objective of project 2:

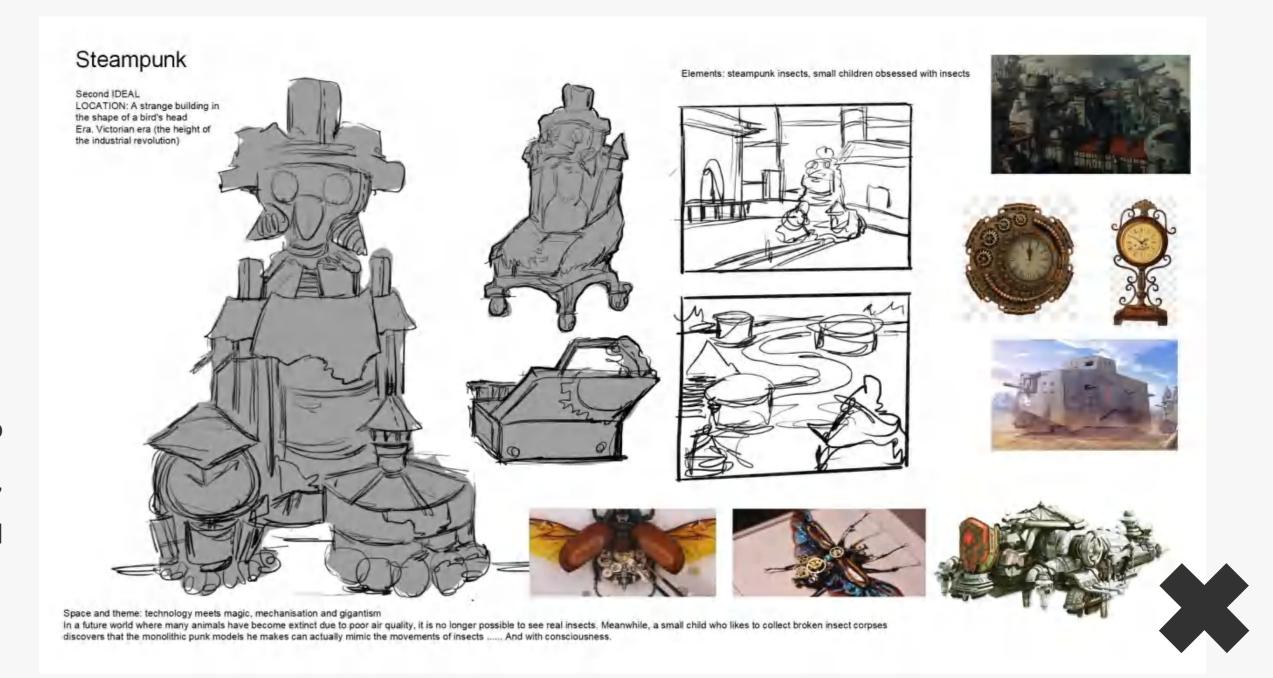
- To complete the animation final modeling\texture\rendering of the scene
- Create a 1 minute animated presentation of the scene
- Revision of character and creature designs and complete model &texture

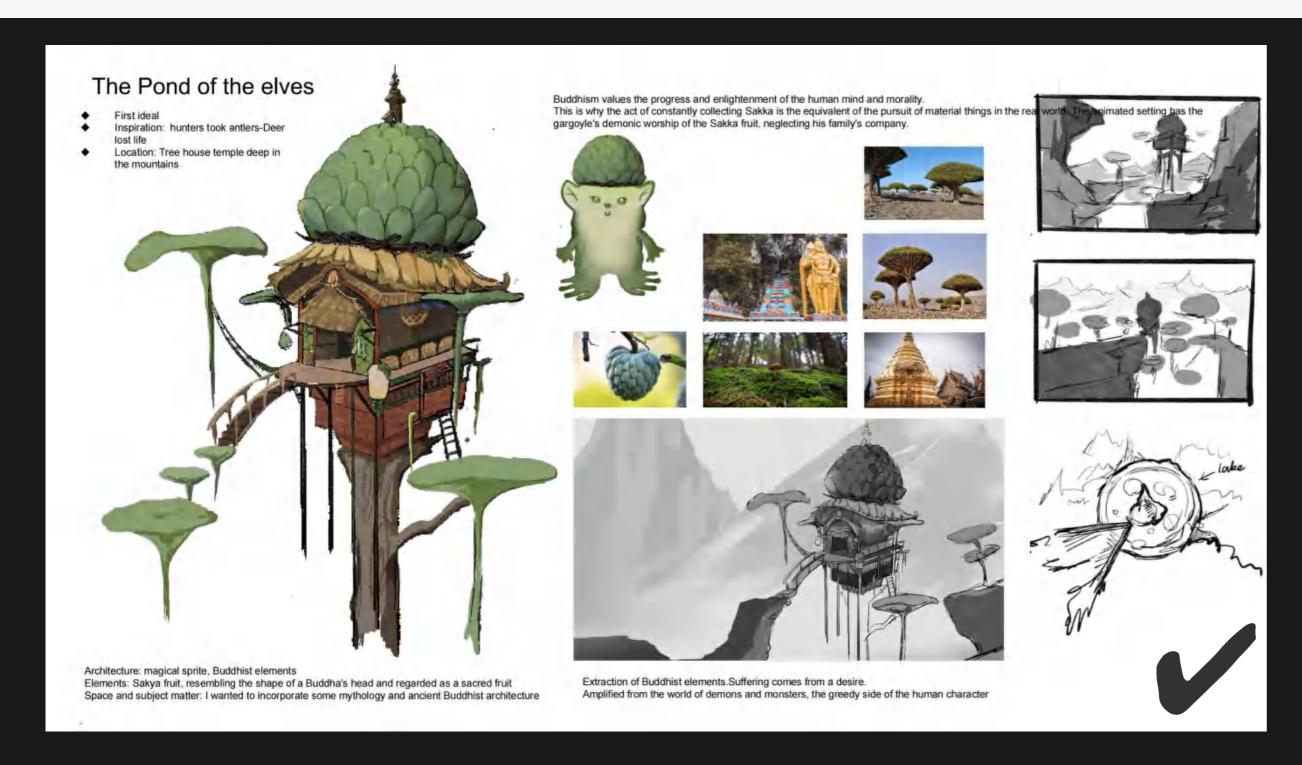
Era: Victorian (the height of the industrial revolution)

Elements: Steampunk insects, children obsessed with mechanical insects

Space and subject matter: technology meets magic, mechanisation and gigantism

In a future world where many animals have died out due to bad air quality, it is no longer possible to see real insects. At the same time, a child, who is very fond of collecting broken insect corpses, discovers one day that the punk model he has made can actually imitate the movement of real insects... and possesses a consciousness.







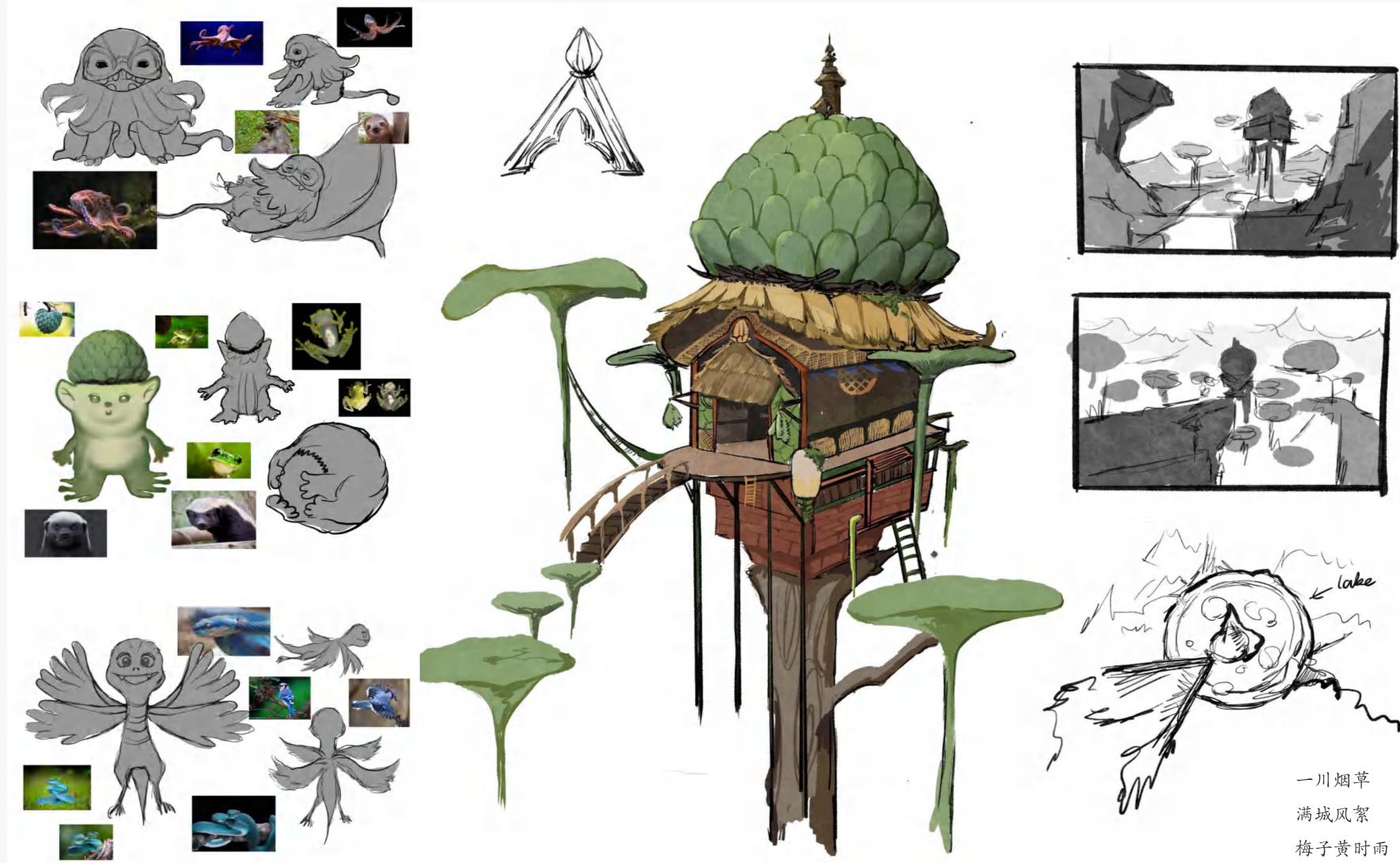
Inspiration & Introduction:

The world is a huge playground for the positive, the more exciting the more fun. For the cowards, it's hell, and you can get hurt anytime, anywhere. So, the kind of world you feel you are in depends on what kind of person you are. By portraying the grey real life and colourful spiritual world of the main character, this story conveys a message that since living by the rules did not bring me the expected happiness. Anxiety and stress were always around me, so why not to break the definition.

Keywords:

Anxiety, Spiritual World, Fantasy Forest, Strange creatures



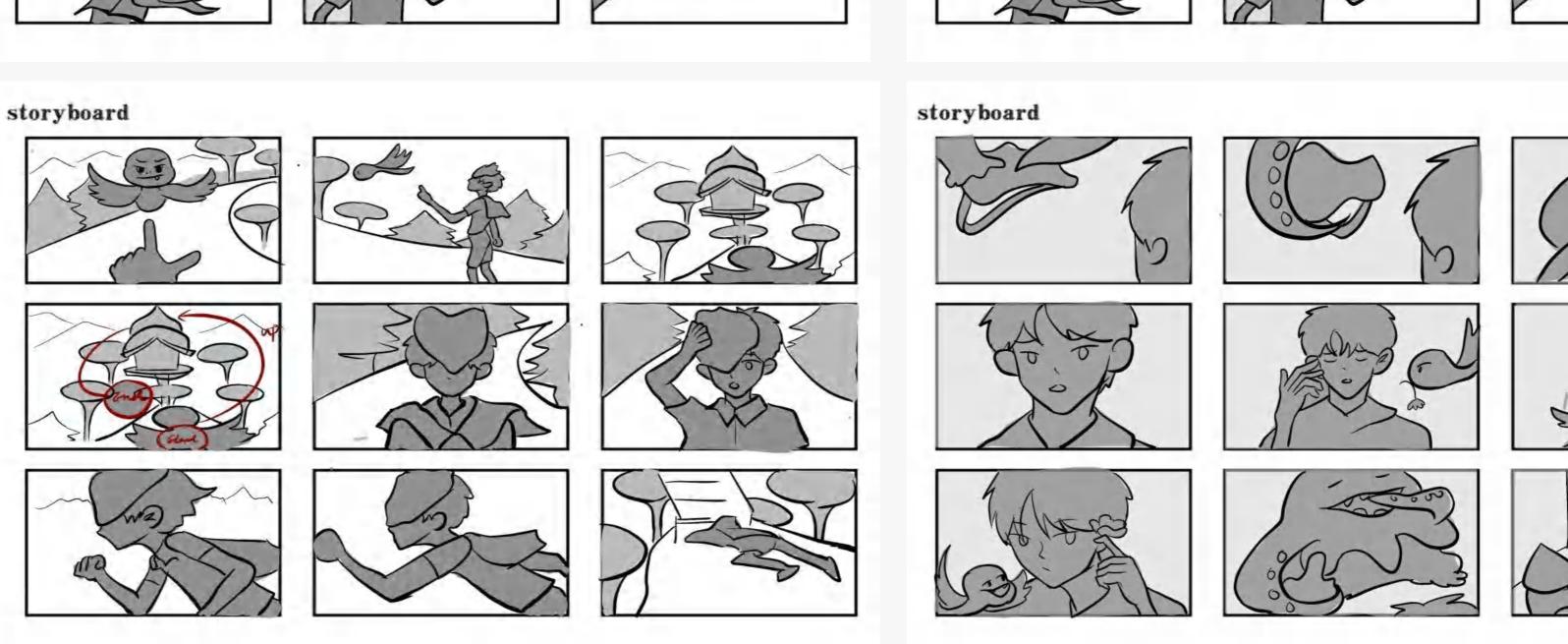


Summary:

People have so many things that bother them. How talented do you have to be to be considered talented? So I still want this film to be light-hearted, healing, and use lots of strange, cute creatures, play to animation's unique strengths in creativity, and focus on exploring the emotional connection between animation and the audience.

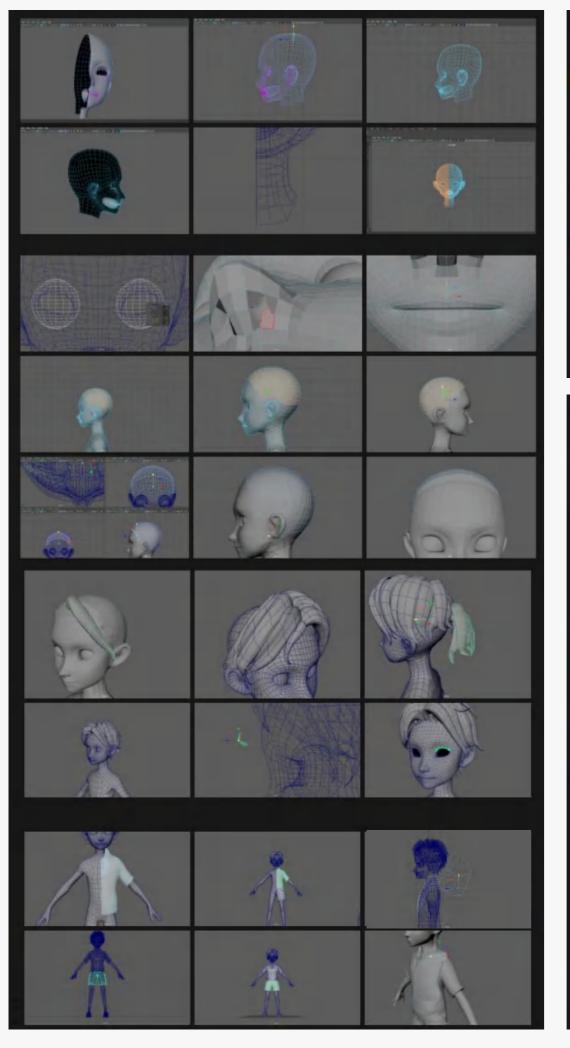
storyline: A boy breaks into a forest. The boy walks carefully in the forest, and suddenly he finds a strange octopus lying in a pond, just then a small flying dragon that looks like a fat panda or cat towards him and leads him deeper into the forest. However, the moment he gets close to the tree house, all kinds of strange little animals approach him, and he has the happiest time in the forest, but will eventually go back to the real world.

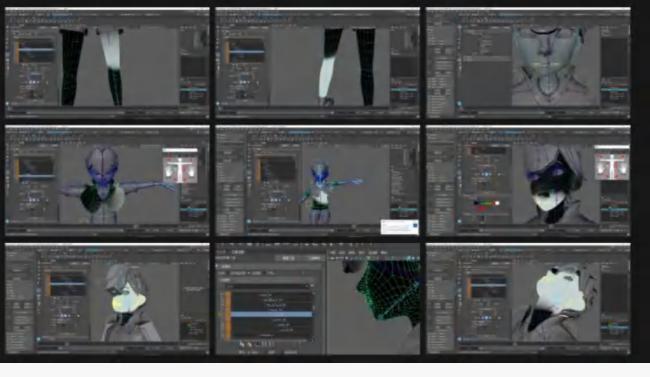
story board The story

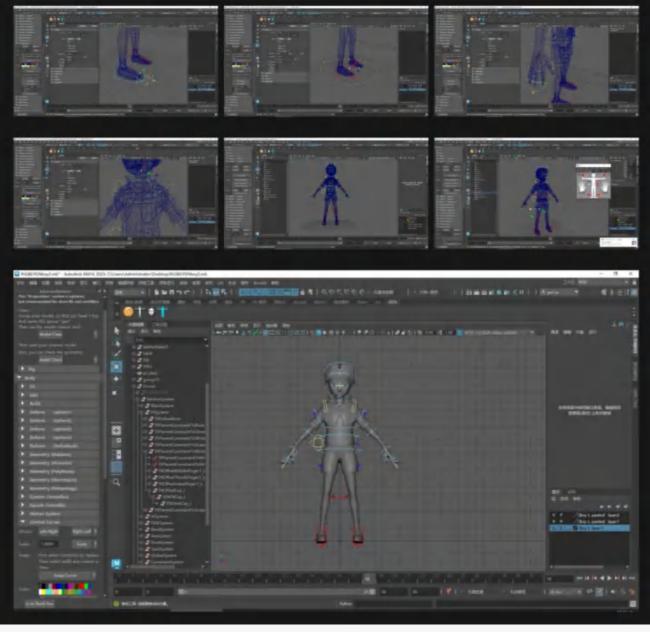


storyboard

Character design-modeling &rigging process







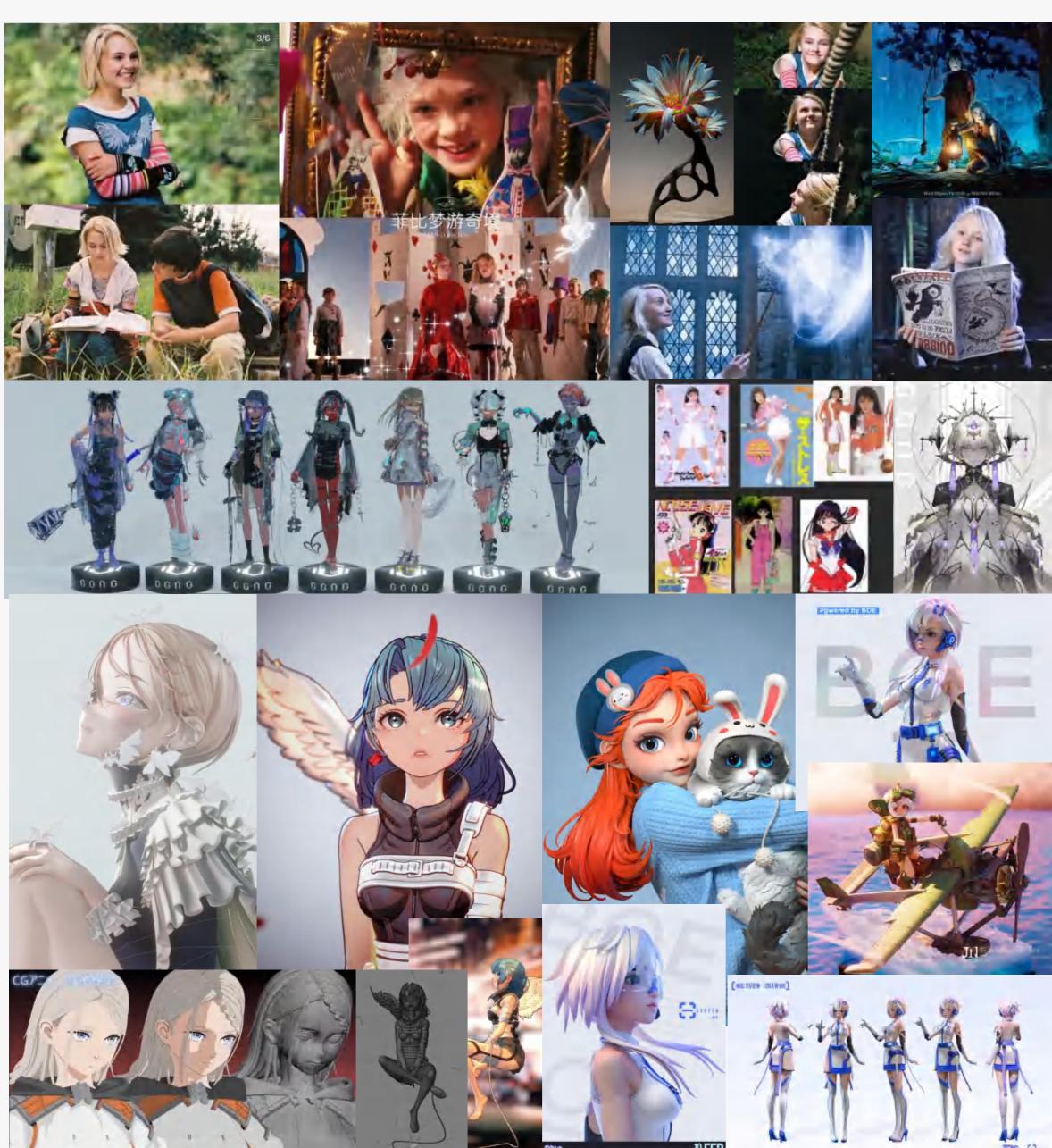






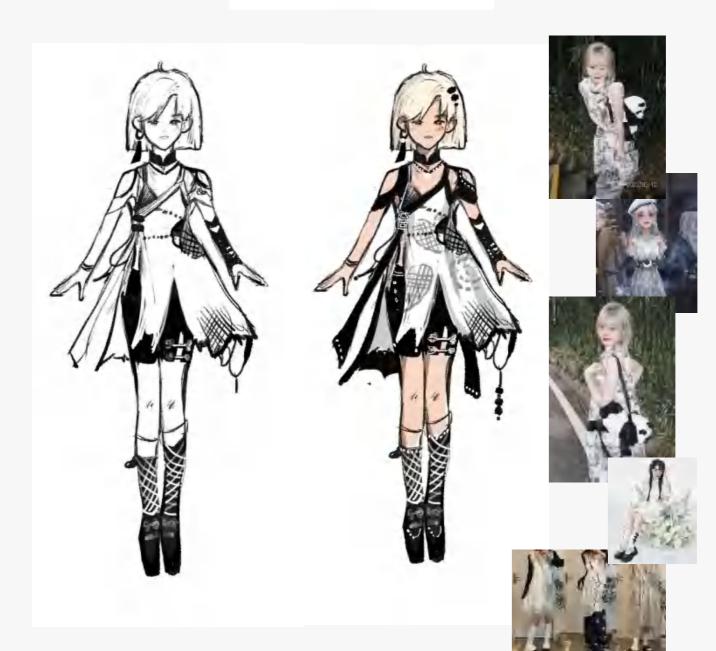
Term 3: Modifications to the character model

Image reference and two rendered materials (cartoon material for flaky hair, 3D realistic material made with xgen)

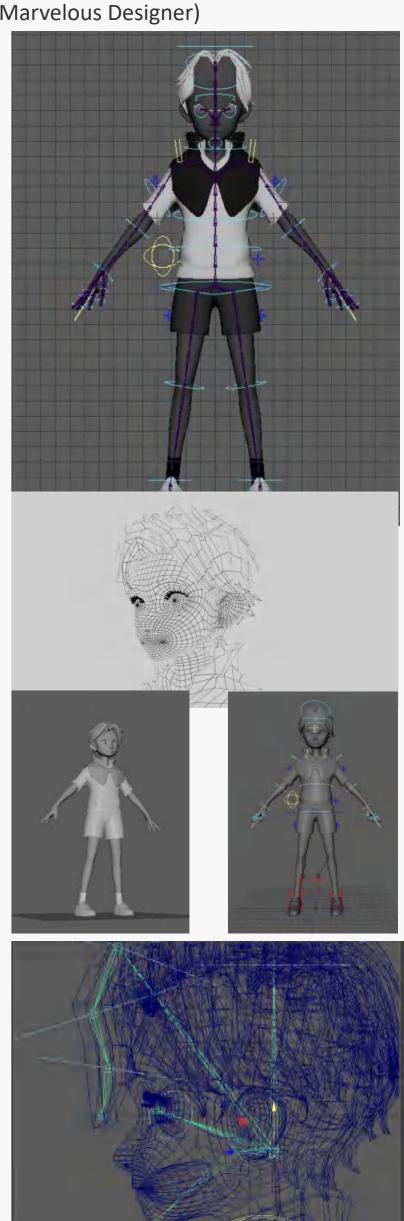


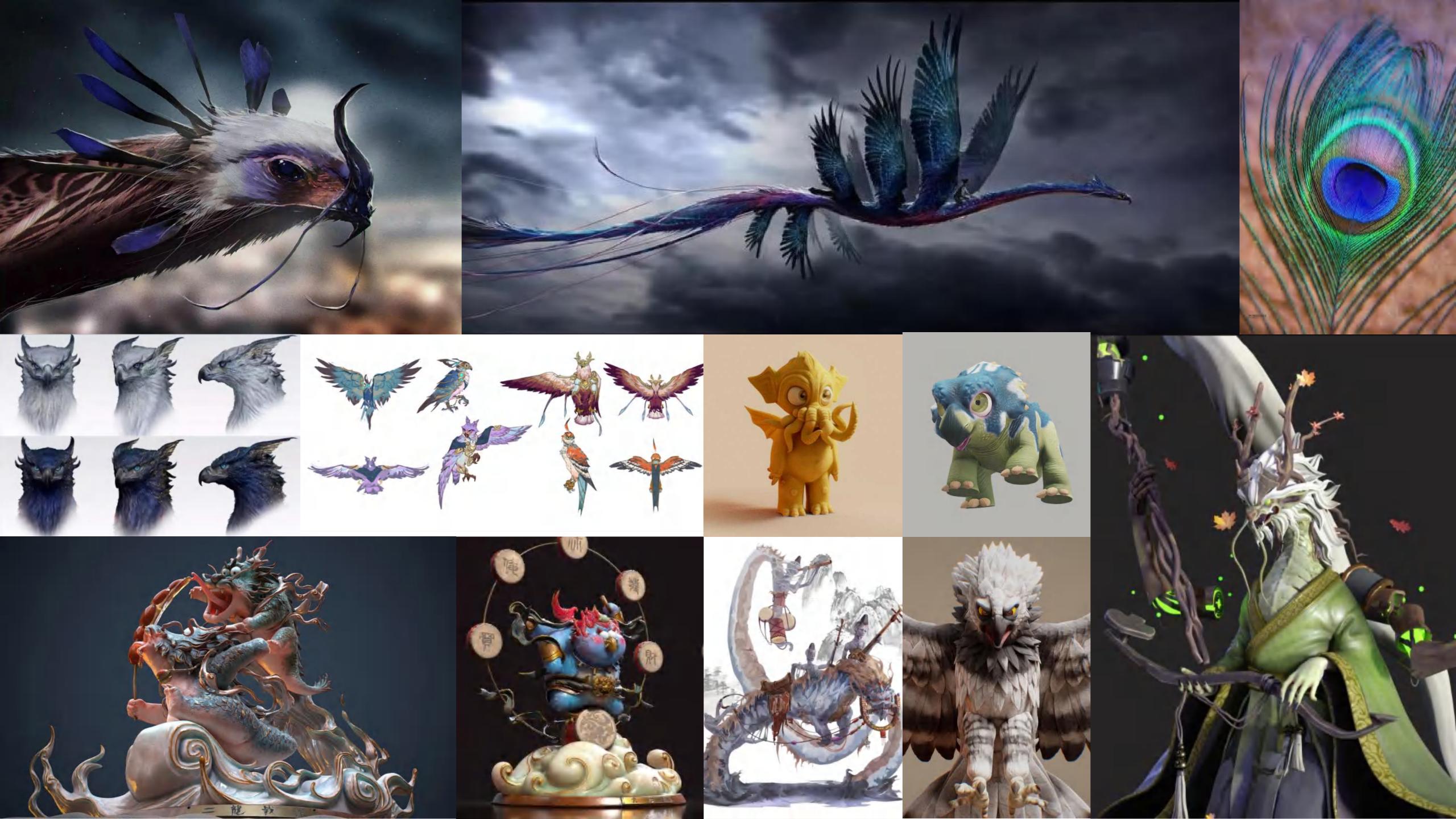
Second sketch (not the final design)



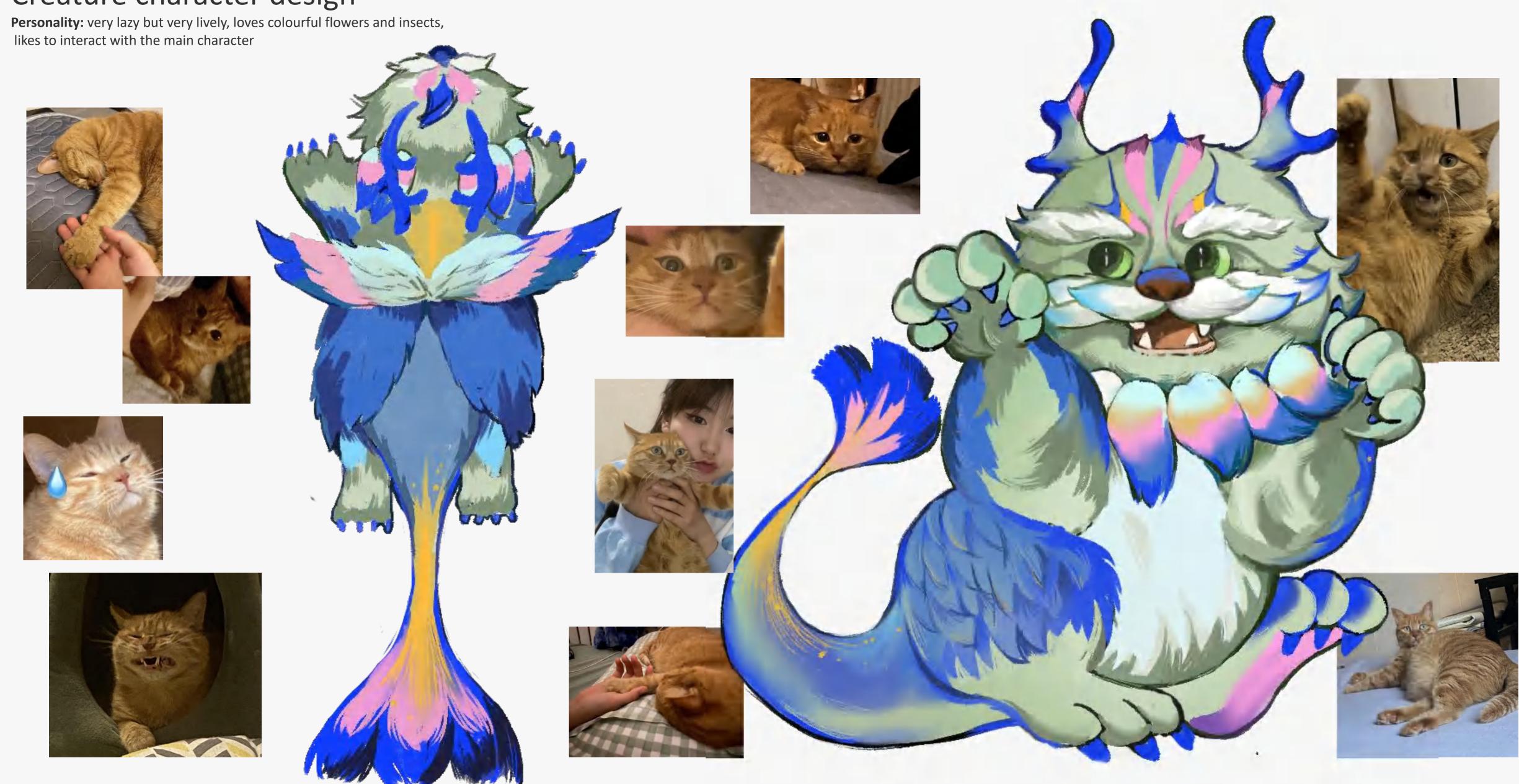


Current model (recreated clothes with Marvelous Designer)





Creature character design



Reference for Creature design

Appearance: Has fluffy fur, looks like a dragon and a cat, a big beautiful tail and small furry wings

Habits: very panda-like, likes to float in the air and sleep







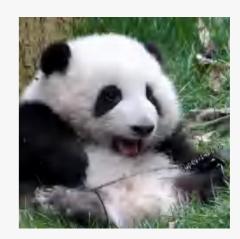


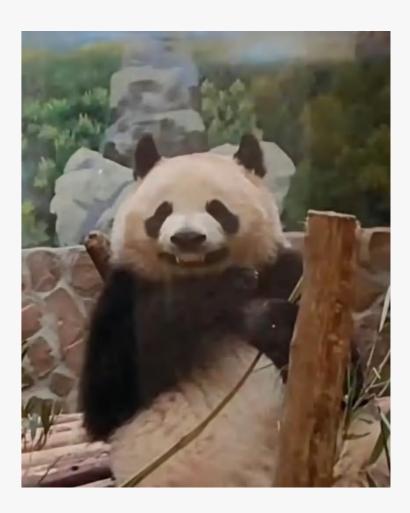






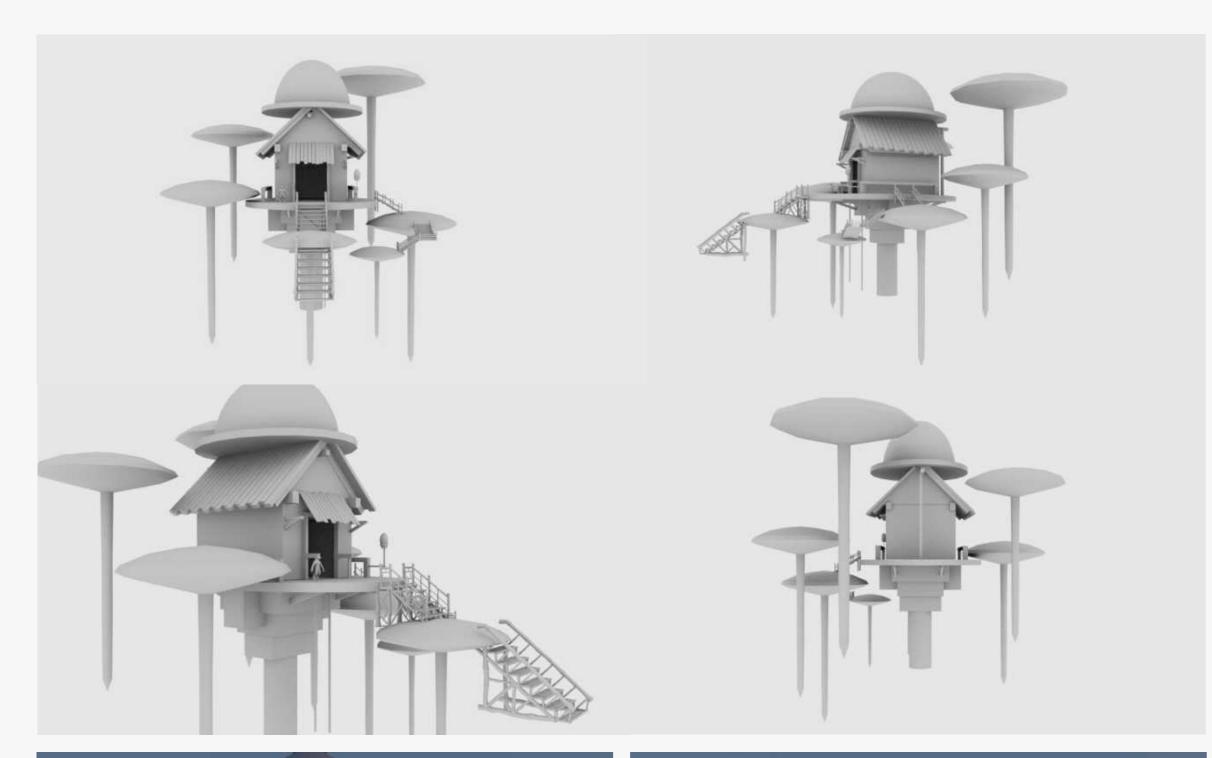






Objective of project 2:

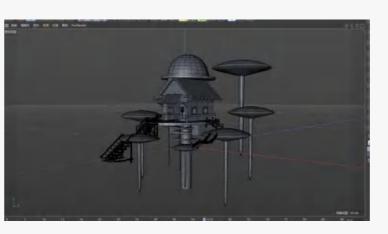
Environmental design

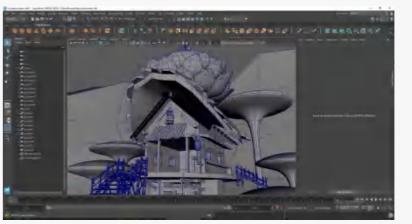


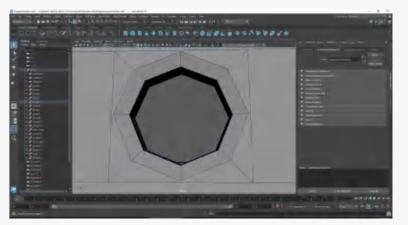




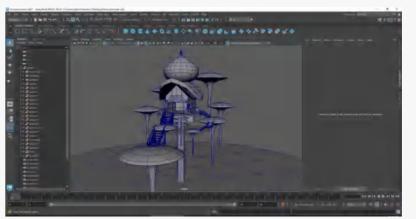
- To complete the animation final modeling\texture\rendering of the scene
 - Create a 1 minute animated presentation of the scenery shot
- Revision of character and creature designs and complete model &texture

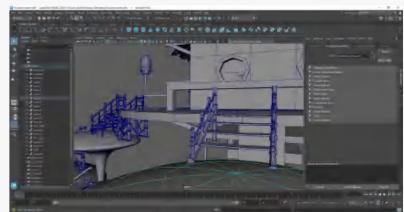


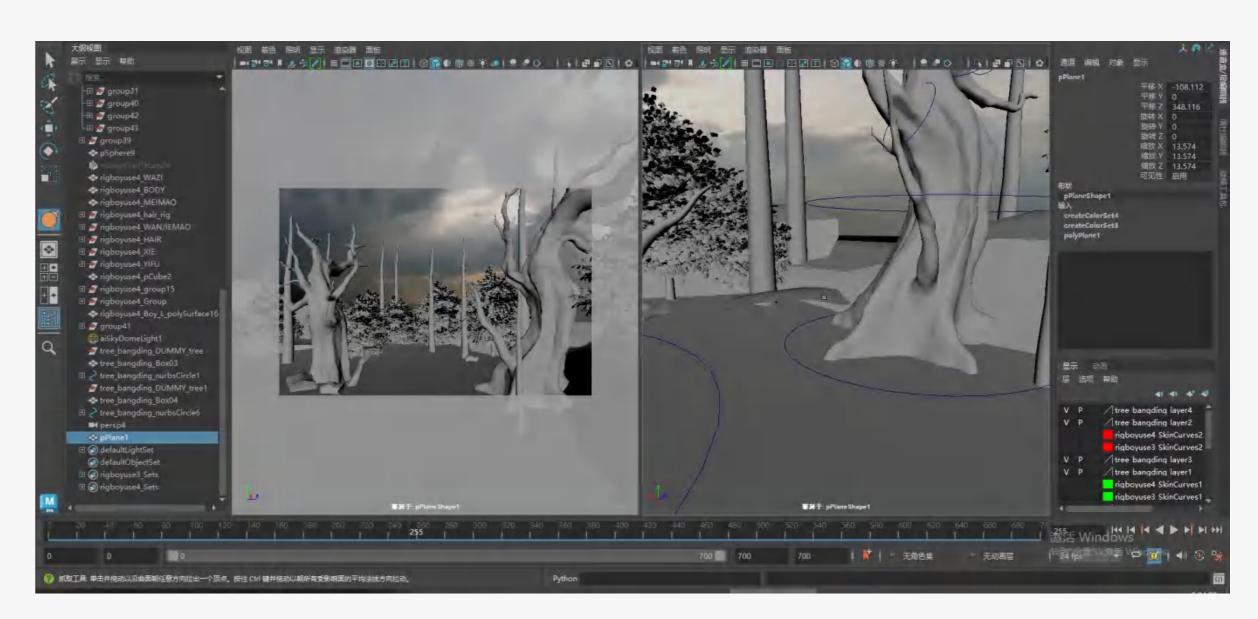
















https://youtu.be/YipxR3dOTW0









